- 12. The method of claim 6, further comprising: determining a resource distribution for distributing resources between the first UAV and the second UAV while coupled.
- 13. The method of claim 12, wherein the resources include at least one of: a power module, a computing component, a navigation component, a camera, a motor, or a control system.
 - 14. The method of claim 6, further comprising:
 - determining, based at least in part on the coupling between the first UAV and the second UAV, a rotational speed for at least one motor of a plurality of motors of the first UAV.
- 15. The method of claim 6, wherein coupling the first UAV and the second UAV is done during aerial transport of the item.
 - 16. A computer implemented method, comprising:
 - under control of one or more computing systems configured with executable instructions,
 - determining a plurality of unmanned aerial vehicles ("UAV") each having a complementary flight plan during a defined time window;
 - determining a collective UAV configuration in which each UAV of the plurality of UAVs is coupled to at least one other UAV of the plurality of UAVs; and

- instructing each of the plurality of UAVs to couple with at least one other UAV of the plurality of UAVs according to the collective UAV configuration to form a collective UAV.
- 17. The computer implemented method of claim 16, further comprising:
 - determining a collective UAV resource distribution for the collective UAV; and
 - instructing each of the plurality of UAVs to distribute resources according to the collective UAV resource distribution.
- 18. The computer implemented method of claim 16, further comprising:
 - instructing each of the plurality of UAVs to aerially navigate while coupled to the at least one other UAV of the plurality of UAVs.
- 19. The computer implemented method of claim 16, wherein at least one of the plurality of UAVs is coupled to an item that is to be aerially transported to a delivery destination.
- 20. The computer implemented method of claim 16, wherein at least one of the plurality of UAVs is not coupled to an item that is to be aerially transported to a delivery destination.

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